

Amendments to the Claims:

This listing of claims replaces all prior versions and listings of claims in the application:

Listing of Claims:

1. (Currently Amended) A computer-implemented distortion compensation method comprising:

determining, on a computing device, an undisturbed phase for at least one of a first position indication signal and a second position indication signal;

determining an undisturbed amplitude ratio that relates the amplitude of the first position indication signal at a first frequency to the amplitude of the second position indication signal at a second frequency, wherein the second frequency is different from the first frequency;

determining a disturbed amplitude and phase of the a position indication signal of at least one sensor; and

adjusting a the position indication signal of the at least one sensor based on the disturbed amplitude and phase, the undisturbed amplitude ratio, and the undisturbed phase.

2. (Original) The method of claim 1 further comprising calculating a relationship between the phases of the first position indication signal and the second position indication signal.

3. (Currently Amended) The method of claim 1 further comprising:

determining a second undisturbed ratio that relates the amplitude of either of the first and the second position indication signals to the amplitude of a third position indication signal at a third frequency, and

adjusting a the position indication signal of the at least one sensor is further based on the second undisturbed ratio.

4. (Original) The method of claim 1 wherein the first frequency is a superior harmonic of the second position indication signal and the second frequency is a subordinate harmonic of the first position indication signal.

5. (Original) The method of claim 4 wherein the superior harmonic is the fundamental frequency.

6. (Original) The method of claim 4 wherein the subordinate harmonic is a third order harmonic.

7. (Original) The method of claim 1 wherein the first frequency is less than the second frequency.

8. (Original) The method of claim 1 further comprising generating a plurality of frequencies using a multiple frequency waveform.

9. (Original) The method of claim 8 wherein the multiple frequency waveform is a chirped waveform.

10. (Original) The method of claim 1 wherein the selected first frequency and second frequency are harmonically related.

11. (Original) The method of claim 1 wherein the distortion compensation method is repeated for a plurality of position indication signals.

12. (Original) The method of claim 1 further comprising detecting the presence of an eddy current in a conductive object.

13. (Original) The method of claim 12 wherein detecting the presence of an eddy current includes monitoring a ratio of the amplitude of the first position indication signal and the amplitude of the second position indication signal.

14. (Original) The method of claim 12 wherein detecting the presence of an eddy current includes detecting a change in the undisturbed phase.

15. (Original) The method of claim 1 wherein determining the undisturbed phase includes measuring asymptotic phase values and using the asymptotic phase values to calculate the undisturbed phase.

16. (Original) The method of claim 15 wherein determining the undisturbed phase includes iteratively calculating phase values and adjusting an asymptotic phase value, the asymptotic phase value used to calculate the undisturbed phase.

17. (Currently Amended) The method of claim 1 further comprising receiving from a the at least one sensor the real and imaginary components of the first and second position indication signals.

18-37. (Canceled)

38. (Withdrawn) A computer assisted coordinate measurement system comprising:
a magnetic tracking system configured to:

determine an undisturbed phase for at least one of a first position indication signal and a second position indication signal; and

determine a disturbed amplitude and phase of the position indication signal; and

a computer configured to:

determine an undisturbed ratio that relates the amplitude of the first position indication signal at a first frequency to the amplitude of the second position indication signal at a second frequency; and
adjust a position indication based on the disturbed amplitude and phase, the undisturbed amplitude ratio, and the undisturbed phase.

39. (Withdrawn) The computer assisted coordinate measurement system of claim 38, wherein the computer is further configured to:

calculate a relationship between the phases of the first position indication signal and the second position indication signal.

40. (Withdrawn) The computer assisted coordinate measurement system of claim 38, wherein the computer is further configured to:

determine a second undisturbed ratio that relates the amplitude of either of the first and the second position indication signals to the amplitude of a third position indication signal at a third frequency, and

adjust a position indication is further based on the second undisturbed ratio.

41. (Withdrawn) The computer assisted coordinate measurement system of claim 38, wherein the first frequency is a superior harmonic of the second position indication signal and the second frequency is a subordinate harmonic of the first position indication signal.

42. (Withdrawn) The computer assisted coordinate measurement system of claim 41, wherein the superior harmonic is the fundamental frequency.

43. (Withdrawn) The computer assisted coordinate measurement system of claim 41, wherein the subordinate harmonic is a third order harmonic.

44. (Withdrawn) The computer assisted coordinate measurement system of claim 38, wherein the first frequency is less than the second frequency.

45. (Withdrawn) The computer assisted coordinate measurement system of claim 38, further comprising:

a waveform generator configured to generate a plurality of frequencies using a multiple frequency waveform.

46. (Withdrawn) The computer assisted coordinate measurement system of claim 45, wherein the multiple frequency waveform is a chirped waveform